## RADIKON

# Versatile Radiation Controller for Industry and Science





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The RADIKON is used to control the value generated by a detector (e.g. radiation sensor or a pressure sensor). If the detector value falls below a certain setpoint value a relay is activated where a valve, an alarm buzzer or other modules can be connected. The **highlight of the RADIKON** is its high versatility making the module very interesting to industrial developers who need to match the controller with different imput signals. The RADIKON can read the generic current of a photodiode (5nA < ISensor <  $5\mu$ A) as well as 0...x Volt and 0(4)....20mA probe signals. The value x is user definable. The RADIKON outputs a voltage of 0....10V which can be used to attach a separate display or to connect the RADIKON with a PID controller. A multicolour LED changes its colour with the radiation intensity level. All these features as well as easy set up and configuration make the RADIKON a perfect tool for developers or manufacturers of small series. For medium series controller modules with customized properties are offered.

Output Values

# Specifications of the RADIKON

Imput Values		Output Values		
	Туре:	Values:	Type:	Properties
	generic sensor signal, e.g.	0x nA	Relay	free floating, 250VAC, 2A
	photodiode current  Voltage input	x can be configured (with jumpers) to 50nA, 150nA, 500nA, 1,5µA und 5µA, other values are possible by soldering an own feedback resistor 0x Volt	Voltage Output	010V
		x can be configured (with jumpers) to 50mV, 142mV, 450mV, 1160mV, 2500mV und 10V other values are possible by soldering an own feedback resistor		
	Current input (current loop)	y20 mA y can be configured (with jumpers) to 0mA or 4mA	multi colour LED	"green" = Value OK "blue" = Value critical "red" = Value too low
	adjustable setpoints	relay setpoint	other LEDs	status of the relay, warmup-
		multi colour LED		delay, activity
	Other properties:			
	Imputs	DC-isolated, EMC and EDS conform	dimensions and weight	$BxHxT = 22,5 \times 99 \times 114,5 \text{ mm}$ (top hat rail EN 50022), m=72g
	Power supply	1224VDC	Conformities	ROHS, CE

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# How to set up the RADIKON

Using the potentiometers "SET POINT HIGH" and "SET POINT LOW" the setpoints for the value "good" = LED is green to value "critical" = LED is blue (SET POINT HIGH) and for the value "critical" to "too low" = LED is red (SET POINT LOW) can be adjusted. Please start with adjusting SET POINT LOW by creating an input value which equals to a signal which is quite between "critical" and "too low". Turning right of the potentiometer shifts the setpoint towards lower signal level and turning left shifts it towards higher signal level. After turning the potentiometer the module needs 5 seconds to store the value. Now your RADIKON is ready to use. Additionally you may also adjust a setpoint for the value "good" to "critical". This feature is particularily interesting if the decline of the signal intensity (e.g. the aging of a lamp) needs be be monitored before the signal is too low. To set the value the source, e.g. the lamp, needs to be adjusted at that point. Now, analogue to the above procedure the setpoint can be configured while turning the SET POINT HIGH potentiometer. The colour of the LED changes from green=good to blue=critical.

## How to use the RADIKON

After powering on the RADIKON a 100ms selftest starts. Then the LED "POWER" is on and a 180s warm up delay starts. During the warm up delay the LED "STATE" is on and the LED "RADIATION" is green. That means that during the first 180s each imput value is interpreted as "good". This feature is important to avoid false alarms during warm up of the lamps to measure. If you need another warm up delay please inform is with your order. After the warm up delay the RADIKON is ready. If the imput value is OK the LED is green, is it critical the LED is blue and is it too low the LED is red and the relay changes its position. If zero imput is present (e.g. sensor failure) the LED blinks red. In case of overrange the LED blinks green.

## The Outputs of the RADIKON

The response the RADIKON calculates based on the imput value can be read using two different methods.

СОМ

## **Relay Output**

The free floating relay output is connected with the terminals "NO" and "COM" if the relay should be "normally open". If "normaly closed" is needed please connect with "NC" and "COM".

## 0-10V - Output

This output is to be connected with the terminals "AO" and "-". You can use this output to connect a display or to use the 0-10V output as actual value imput of a PID regulator.

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## The Inputs of the RADIKON

The RADIKON is able to read all common sensor outputs. Below the wiring for the different sensor outputs is explained:

# Wiring of a Photodiode or another small current source

- Anode (+) to terminal PD+
- Cathode (-) to terminal PD-
- Shielding to terminal –
- please consider that cable length must be as short as possible

#### Configuration of the Photodiode input

If you like to use the generic photodiode input at first you need to know about the typical current coming from your photodiode. The RADIKON works with currents from 50nA and 5µA. By default the unit is set to a typical current of 150nA. If your sensors gives another current please open the RADIKON's housing and remove the PCB. The picture at the right side shows the different jumper positions. If your current is below 50nA or above 5µA please set the jumper to "VAR" and solder a special 0804 SMD resistor calculated by the formula  $R_{\text{VAR}} = 5000\text{/I}$ , where  $R_{\text{VAR}}$  is given in M $\Omega$ , and I, the photodiode current you need is given in nA. The value  $C_{\text{VAR}}$  calculates by  $C_{\text{VAR}} = 0.1\text{s} / R_{\text{VAR}}$ 



Jumper positions for photodiode input

#### Wiring Sensor Voltage 0-10V:

- Anode (+) to terminal AI
- Cathode (-) to terminal –
- Bridge from F2 to +

## Wiring Sensor Voltage 0-x V

- Anode (+) to terminal PD+
- Cathode (-) to terminal PD-

## Configuration of the Voltage input 0-10V:

No configuration is needed. no jumpers must be moved.

## Configuration of the Voltage input 0-xV:

The maximum Value x ist the maximum voltage your sensor outputs. If this max. voltage is not 10V you need to configure another max. voltage with the jumpers as shown at the right side picture. You can select max. values  $x=50\text{mV},\ 142\text{mV},\ 450\text{mV},\ 1160\text{mV}$  or 2500mV. If your max. voltage is below 50mV or above 2,5V please set the jumper to "VAR" and solder a special 0804 SMD resistor calculated by the formula  $R_{VAR}=5000/U$ , where  $R_{VAR}$  is given in  $M\Omega$ , and U, the photodiode current you need is given in mV. The value  $C_{VAR}$  calculates by  $C_{VAR}=0,1s$  /  $R_{VAR}$ 

# Put purper here for. | Put purper here for. | U = 2.5 V | U = 1.10V | U = 1.20V | U = 1.20V | U = 1.20V | U = 5.00V | Edder here Cos. | U = 5.00V | U = 5.00V | Edder here Cos. | U = 5.00V | U = 5.0

Jumper positions for sensor voltage 0-x V input

## Wring Sensor Current 0-20mA:

- Anode (+) to terminal +
- Cathode (-) to terminal AI
- 500  $\Omega$  Resistor from AI to (included in the delivery)
- Bridge from + to F2

#### Wring Sensor Current 4-20mA:

- Anode to terminal +
- Cathode to terminal Al
- 500  $\Omega$  Resistor from AI to –
- Bridge from + to F1

## Configuration of the Sensor Current input 0-20mA:

No configuration is needed. no jumpers must be moved.

# Configuration of the Sensor Current input 4-20mA:

No configuration is needed. no jumpers must be moved.

# Wiring Power Supply 12-24VDC:

terminals + and -

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