



Front view length sensor MLS-8

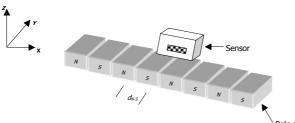
Advantages

- high resolution
- low noise
- low current consumption
- low interference field sensitivity

Applications

- Length measurement for
- direction identification
 Angle measurement with
- pole wheels

Application principle





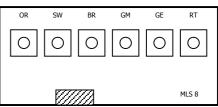
Specification

| Parameter | Condition | Symbol | Min | Тур | Max | Unit |
|---|---------------------------------------|-----------------------------------|------------------|-------|-------|-------|
| Supply voltage | | U _{cc} | | 5 | 10 | V |
| Sensor resistance | | R_s | 30 | 40 | 50 | kΩ |
| Pole distance | | d _{N-S} | | 2.5 | | mm |
| Signal amplitude | by H _{appl} =32kA/m, T=RT | $\Delta U/U_{cc}$ | 8 | | | mV/V |
| Offset voltage | | U _{off} /U _{cc} | | | 1 | mV/V |
| Applied magnetic field | Magnet field distance z<1.5mm | Happl | 10 | | | kA/m |
| Temperature coefficient of amplitude | | TCSV | -0.37 | -0.33 | -0.29 | %/K |
| Temperature coefficient of resistance | | TCBR | 0.29 | 0.33 | 0.37 | %/K |
| Operating temperature | | T _{op} | -40 | | +85 | \Im |
| Storage temperature | | T _{storage} | -55 | | +125 | \Im |
| Dimension | | WxDxL | 17.8 x 8.1 x 2.2 | | mm | |

Description

The magnetoresistive strong field sensor MLS-8 consists of two against each other shifted Wheatstone bridges. They are assembled on a ceramic hybrid. The resistance position at the bridge is fixed by a magnetic scale with a period length (pole distance N-S) of 2.5 mm. The pole stripe with his changing magnetization is guided along the sensor in a distance of z<1.5 mm. Thereby occur output signals with a sine and cosine characteristic. By sine/cosine analysis precise distances in between the pole stripe can be detected. The reachable measurement precision depends on the distance between sensor and pole stripe.

Pin out



| Pin | Mean | Тур |
|-----|----------------|--------------------|
| OR | Output signal | V _{cos2+} |
| SW | Supply voltage | VB |
| BR | Ground | GND |
| GN | Output signal | V _{sin2-} |
| GE | Output signal | V _{sin1+} |
| RT | Output signal | V _{cos1+} |