



- Analog voltage output
- Low profile
- Standard industry package size
- Sleeve bearing
- Custom housings, shafts, connectors available, in most cases with no additional tooling required

DESCRIPTION

The ED-22 series magnetic encoder can be used to replace a conventional potentiometer. This product offers 270 degrees of electrical travel, integrated rotational stop system, 300 degrees of mechanical travel, utilizing a sleeve bearing and shaft fitted with an O-ring seal. This sensor is designed for rotary human machine input (HMI) applications. The Non-contact magnetic sensor design utilized in the ED-22 is well suited for industrial applications where extreme temperatures, high vibration and shock, and contamination are present. The ED-22 is designed using our standard modular and flexible construction methods. We can customize housings, shafts, and terminations to meet your exact specifications at little or no tooling costs.

FEATURES

Magnetic sensing technology

- Encapsulated electronics/sealed unit
- Harsh environment compatibility
- 0 to 5 Vdc outputs
- Consistent rotational torque
- Resistant to contamination
- Highly resistant to vibration
- Metal shaft and bushing
- Wide operational temperature range (-40°C to 85°C)

APPLICATIONS

- Machine tool control
- Paint spraying system control
- Medical equipment
- Industrial test and measuring equipment
- Off highway cab controls
- Marine
- Exercise equipment
- Value positioning
- Industrial joysticks



PERFORMANCE SPECS (NOTE1)

Analog voltage output:

Parameters	ED-22-SB-0050-V-X	
Standard output range 0 - 270°	0 Vdc to 5.0 Vdc	
Supply current	15 mA	
Operating voltage (Vcc)	5 Vdc ± 0.25 Vdc	
Resolution	1.4°	
Accuracy	2.8°	
Operating temperature	-40°C to +85°C	

Bearing:

Parameters	ED-22-SB-0050-V-X	
Bearings	Sleeve	
Maximum speed	300 RPM	
Bearing life	3,000,000 cycles	

(NOTE1): All specifications are specified with Vcc @ Nominal input voltage, and Ambient Temperature 25 Degrees Celsius.

MECHANICAL SPECS

Parameters	ED-22-SB-0050-V-X	
Axial load (max)	20 N	
Radial load (max)	10 N	
Shaft end play axial (max)	0.13 mm	
Shaft radial play (max)	0.25 mm (15.3 mm from thread)	
Shaft push-in force	9 N	
Shaft pull-out force	1.3 N	
Run out (max.)	0.25 mm (19 mm from thread)	
Bushing mounting torque	1.1 Nm	



DIMENSIONS

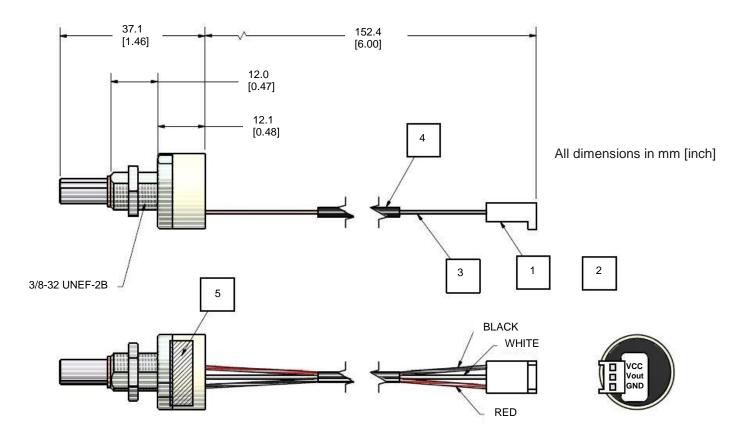
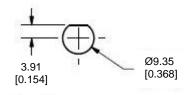


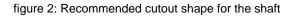
figure 1: Dimension of the ED-22 (side view)

Notes	Description
1	Housing - MOLEX #22-01-3037
2	Terminals - (3X) MOLEX #08-55-0102 or # 08-55-0101
3	Wire - 24 AWG stranded copper with TFE or FEP insulation
4	Heat shrink wires leaving both ends exposed min 1.0" free
5	Encoder label





All dimension s in mm [ich]



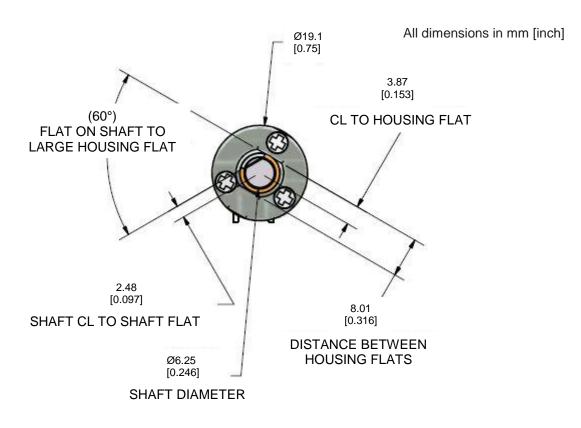


figure 3: Dimension of the ED-22 (front view)



TYPICAL PERFORMANCE CURVES

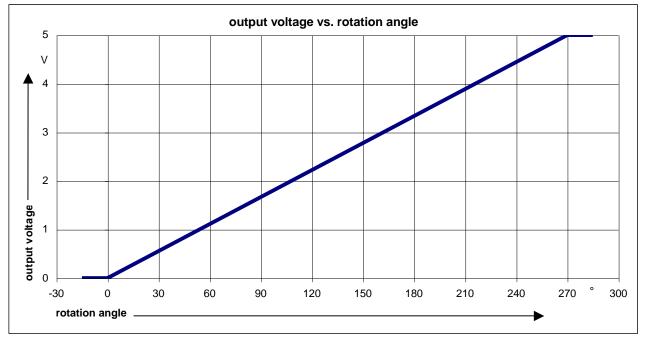


figure 4: Output voltage vs. rotation angle

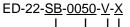
ENVIRONMENTAL

Vibration	MIL-STD-202F Method 204D	
VIDIATION	Test Condition B	
Shock	MIL-STD-202F Method 213B	
	Test Condition C	
Humidity	MIL-STD-202F Method 103B	
	Test Condition A	
Thermal Shock	MIL-STD-202F Method 107G	
Thermal Shock	Test Condition A	
Operating Temperature	-40 to +85°C	
Storage Temperature	-55 to +125°C	



ORDERING INFORMATION

PART NUMBERING Model Number - Bearing - Range - Analog Output - Connection





Connection Analog Output Output Range Bearing Options: P = Pin header C = Cable V = Voltage 0050 = 0 Vdc to 5.0 VdcSB = Sleeve bearing

Example: ED-22-<u>SB-0050-V-P</u>

Model ED-22, sleeve bearing, analog output voltage from 0 Vdc to 5 Vdc, pin header

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