# RADIKON

Versatile radiation controller for industry and science



1/3

### **GENERAL FEATURES**



### **Properties of the RADIKON**

The RADIKON is used to control the value generated by a detector (e.g. radiation sensor or a pressure sensor). If the detector value falls below a certain setpoint value a relay is activated where a valve, an alarm buzzer or other modules can be connected. The highlight of the RADIKON is its high versatility making the module very interesting to industrial developers who need to match the controller with different imput signals.

The RADIKON can read the generic current of a photodiode (5nA < ISensor < 5µA) as well as o...x Volt and o(4)...2omA probe signals. The value x is user definable. The RADIKON outputs a voltage of o...1oV which can be used to attach a separate display or to connect the RADIKON with a PID controller. A multi-colour LED changes its colour with the radiation intensity level. All these features as well as easy set up and configuration make the RADIKON a perfect tool for developers or manufacturers of small series. For medium series controller modules with customized properties are offered.

### SPECIFICATIONS

| INPUT VALUES Parameter                            | Value  |
|---|--|
| Generic sensor signal,<br>e.g. photodiode current | o to x nA  |
|   | x can be configured (with jumpers) to 50 nA, 150 nA, 500 nA, 1.5 $\mu A$ and 5 $\mu A$ , other values are possible by soldering an own feedback resistor |
| Voltage input                                     | o to x Volt  |
|   | x can be configured (with jumpers) to 50 mV, 142 mV, 450 mV, 1160 mV, 2500 mV and 10 V, other values are possible by soldering an own feedback resistor  |
| Current input (current loop)                      | y to 20 mA   |
|   | y can be configured (with jumpers) to o mA or 4 mA   |
| Adjustable setpoints                              | relay setpoint, multi colour LED   |
| <b>Other Properties</b>                           |  |
| Inputs  | DC-isolated, EMC and EDS conform   |
| Power supply                                      | 12 to 24 VDC   |



## RADIKON

Versatile radiation controller for industry and science



2/3

HOW TO SET UP

Using the potentiometers "SET POINT HIGH" and "SET POINT LOW" the setpoints for the value "good" = LED is green to value "critical" = LED is blue (SET POINT HIGH) and for the value "critical" to "too low" = LED is red (SET POINT LOW) can be adjusted. Please start with adjusting SET POINT LOW by creating an input value which equals to a signal which is quite between "critical" and "too low". Turning right of the potentiometer shifts the setpoint towards lower signal level and turning left shifts it towards higher signal level. After turning the potentiometer the module needs 5 seconds to store the value. Now your RADIKON is ready to use. Additionally you may also adjust a setpoint for the value "good" to "critical". This feature is particularily interesting if the decline of the signal intensity (e.g. the aging of a lamp) needs be be monitored before the signal is too low. To set the value the source, e.g. the lamp, needs to be adjusted at that point. Now, analogue to the above procedure the setpoint can be configured while turning the SET POINT HIGH potentiometer. The colour of the LED changes from green=good to blue=critical.

### HOW TO USE

After powering on the RADIKON a 100ms selftest starts. Then the LED "POWER" is on and a 180 s warm up delay starts. During the warm up delay the LED "STATE" is on and the LED "RADIATION" is green. That means that during the first 180s each imput value is interpreted as "good". This feature is important to avoid false alarms during warm up of the lamps to measure. If you need another warm up delay please inform is with your order. After the warm up delay the RADIKON is ready. If the imput value is OK the LED is green, is it critical the LED is blue and is it too low the LED is red and the relay changes its position. If zero imput is present (e.g. sensor failure) the LED blinks red. In case of overrange the LED blinks green.

### POWER SUPPLY

A power supply of 12-24VDC is required. Positive pole goes to terminal + and supply ground to terminal -.

### **OUTPUT CONNECTIONS**

The response the RADIKON calculates based on the input value can be read using two different methods.

### **Relay Output**

The free floating relay output is connected with the terminals "NO" and "COM" if the relay should be "normally open". If "normally closed" is needed please connect with "NC" and "COM".



### o - 10 V - output

This output is to be connected with the terminals "AO" and "-". You can use this output to connect a display or to use the o-10V output as actual value input of a PID regulator.



## RADIKON

Versatile radiation controller for industry and science

### INPUT CONNECTIONS

The RADIKON is able to read all common sensor outputs. Below the wiring for the different sensor outputs is explained:

## Wiring of a Photodiode or another small current source

- Anode (+) to terminal PD+
- Cathode (-) to terminal PD-
- Shielding to terminal –
- please consider that cable length must be as short as possible

### **Configuration of the photodiode input**

If you like to use the generic photodiode input at first you need to know about the typical current coming from your photodiode. The RADIKON works with currents from 5onA and 5µA. By default the unit is set to a typical current of 15onA. If your sensor gives another current please open the RADIKON's housing and remove the PCB. The picture at the right side shows the different jumper positions. If your current is below 5onA or above 5µA please set the jumper to "VAR" and solder a special o8o4 SMD resistor calculated by the formula  $R_{VAR} = 5000/I$ , where  $R_{VAR}$  is given in MOhm, and I, the input current you need is given in nA. The value  $C_{VAR}$  calculates by  $C_{VAR} = 0.15/R_{VAR}$ 

### Собитиет Сал албаниет Сал Собитиет Сал С

Jumper positions for photodiode input

### Wiring sensor voltage o-10V:

- Anode (+) to terminal AI
- Cathode (-) to terminal –
- Bridge from + to F2

### Wiring sensor voltage o-x V

- Anode (+) to terminal PD+
- Cathode (-) to terminal PD-

### Configuration of the voltage input o-xV:

The maximum value x ist the maximum voltage your sensor outputs. If this max. voltage is not 10V you need to configure another max. voltage with the jumpers as shown at the right side picture. You can select max. values x = 50mV, 142mV, 450mV, 1160mV or 2500mV. If your max. voltage is below 50mV or above 2.5V please set the jumper to "VAR" and solder a special 0804 SMD resistor calculated by the formula  $R_{VAR} = 5000/U$ , where  $R_{VAR}$  is given in MOhm, and U, the input voltage you need is given in mV. The value  $C_{VAR}$  calculates by  $C_{VAR} = 0.15/R_{VAR}$ 

### Configuration of the sensor current input o-20mA:

No configuration is needed. No jumpers must be moved.

### Wiring sensor current o-20mA:

- Anode (+) to terminal +
- Cathode (-) to terminal AI
- 500Ohm- Resistor from AI to (included in the delivery)
- Bridge from + to F2

### Wiring sensor current 4-20mA:

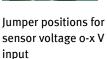
- Anode (+) to terminal +
- Cathode (-) to terminal AI
- 500 Ohm- Resistor from AI to -
- Bridge from + to F1

### Configuration of the sensor current input 4-20mA:

No configuration is needed. No jumpers must be moved.













No configuration is needed. No impers must be m

No configuration is needed. No jumpers must be moved.